

Influence of input parameters on characteristics of EDM process

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This paper presents the results of experimental studies carried out to conduct a comprehensive investigation on the influence of Electrical Discharge Machining (EDM) input parameters on characteristics of EDM process. The studied process characteristics included machining features, embracing material removal rate, tool wear ratio, and arithmetical mean roughness, as well surface integrity characteristics comprising of the thickness of white layer and the depth of heat affected zone of AISI H13 tool steel as workpiece. The experiments performed under the designed full factorial procedure, and the considered EDM input parameters included pulse on-time and pulse current. The results of this study could be utilized in the selection of optimum process parameters to achieve the desired EDM efficiency, surface roughness, and surface integrity when machining AISI H13 tool steel.

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0 Introduction

Considering the challenges brought on by advanced technology, the Electrical Discharge Machining (EDM) process is one of the best alternatives for machining an ever increasing number of high-strength, non-corrosion, and wear resistant materials [1, 2]. AISI H13 tool steel is considered a significant one of these materials that has a widespread application in mold industries [3].

Electrical discharge machining utilizes rapid, repetitive spark discharges from a pulsating direct-current power supply between the workpiece and the tool submerged into a dielectric liquid [4]. The thermal energy of the sparks leads to intense heat conditions on the workpiece causing melting and vaporizing of workpiece material. Due to the high temperature of the sparks, not only work material is melted and vaporized, but the electrode material is also melted and vaporized, which is known as tool wear. The tool wear process is quite similar to the material removal mechanism of the workpiece as the tool and the workpiece are considered as a set of electrodes in EDM process. Due to this wear, tool loses its dimensions resulting in inaccuracy of the cavities formed on the workpiece. Consequently, during the EDM process, the main machining output parameters are the material removal rate (MRR), tool

wear ratio (TWR) and surface roughness (R_a) of the workpiece. It is desirable to obtain the maximum MRR with minimum TWR and surface roughness [5].

Furthermore, at the end of each discharge, depending on the plasma flushing efficiency (%PFE) or the ability of plasma channel in removing molten material from the molten material crater, collapsing of the plasma channel causes very violent suction and severe bulk boiling of some of the molten material and removing them from the molten crater [6]. The material remaining in the crater re-solidifies, which is called the “white layer” or “recast layer”, and develops a residual stress that often causes micro cracks. An annealed Heat Affected Zone (HAZ) lay directly below the recast layer. The micro cracks created in the white layer could penetrate into the HAZ. Additionally, this layer is softer than the underlying base material. This annealed zone could weaken prematurely and cause the material to develop stress fractures that could lead to anything from a minor malfunction to a catastrophic failure. Since the quality of an ED machined surface is becoming more and more important to satisfy the increasing demands of sophisticated component performance, longevity and reliability [7, 8], the optimum utilization of the EDM process requires the

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selection of an appropriate set of machining parameters that would result in the minimum thickness of the recast layer and depth of heat affected zone [9].

This paper aims to fill the gap in the existing literature with respect to the processing of AISI H13 tool steel with EDM. In particular, EDM machining experiments were conducted on AISI H13 samples having a hardness of 52.7HRC using copper electrode to investigate the correlations between the EDM parameters (pulse on-time and current) and the EDM characteristics of such a workpiece. The output factors investigated were the material removal rate, tool wear ratio, surface roughness, as well as the thickness of white layer and depth of heat affected

zone of EDMed workpiece. This experimental study results in the selection of optimum process parameters to achieve the desired EDM efficiency, surface roughness, and surface integrity when machining such a workpiece material.

1 Experimental setup and procedure

The workpiece material used in this study was AISI H13 tool steel. Prior to EDM processing, the workpiece was cut in a cylindrical shape with a length of 20mm and a diameter of 20mm. The main mechanical and physical properties of such a workpiece material at different temperatures are given in Table (1).

Table 1. Mechanical and physical properties of AISI H13 [10].

Temperature °C	Density kg/dm ³	Specific heat J/(kg .K)	Electrical resistivity Ohm.mm ² /m	Modulus of elasticity N/mm ²	Thermal conductivity (W/m.K)
20°C	7.80	460	0.52	215×10 ³	24.30
500°C	7.64	550	0.86	176×10 ³	27.70
600°C	7.60	590	0.96	165×10 ³	27.50
Liquidus temperature		1454 ⁰ C	Solidus temperature		1315 ⁰ C

The tool material was forged commercial pure copper with the main properties given in Table (2). The experiments were performed on a die sinking EDM machine (CHARMILLES ROBO-FORM200) which operates with an iso-pulse generator. Machining tests were carried out at five pulse current settings, as well as four pulse on-time settings. As a result, 20 experiments could be designed. Each machining test was performed for 15 minutes. Table (3) presents the experimental test conditions.

A digital balance (CP2245-Surtoorius) with a resolution of 0.1mg was used for weighing the workpieces before and after the machining process. The tool wear ratio is defined as the volume of material removed from the tool (V_E) divided by the volume of material removed from the workpiece

(V_W). Eqs. (1) and (2) show the calculations used for assessing the values of MRR and TWR.

$$MRR = (M_1 - M_2) / (\rho_w \cdot T) \quad (1)$$

$$TWR = (V_E / V_W) \cdot 100 \% \quad (2)$$

where M_1 and M_2 are the weight of workpiece before and after machining (g), respectively. ρ_w is the density of workpiece (g/mm³), and T is the machining time (min).

According to Lee and Tai [12], the amount of white layer thickness (WT) has been measured by measuring this layer's thickness at 30 different points by utilizing VEGA\TESCAN scanning electron microscopy (SEM) and accounting for their average (Figs. 1-3). So the machined specimens were sectioned transversely by a wire electrical discharge

machine and prepared under a standard procedure for metallographic observation. Etching was performed by immersing the specimens in 5% Nital reagent.

On the other hand, according to Hascalyk and Caydas [13], since there are not much significant differences between HAZ and parent material in the microscopic images that could be identified by, measuring of micro-hardness is a reasonable way to

obtain the depth of heat affected zone (HD). With this in mind, micro-hardness from cross-section of machined specimens was measured to determine the depth of heat affected zone. The micro-hardness of specimens was measured by the OLYMPUS LM700 micro-hardness tester. The values of WT and HD are represented in Table (4).

Table 2. Physical properties of copper electrode [11].

Physical properties	Copper
Thermal conductivity (W/m. ⁰ K)	380.7
Melting point (⁰ C)	1083
Boiling temperature (⁰ C)	2595
Specific heat (cal/g. ⁰ C)	0.092
Specific gravity at 20 ⁰ C (g/cm ³)	8.9
Coefficient of thermal expansion ($\times 10^{-6}$ ⁰ C ⁻¹)	17

Table 3. Experimental test conditions.

Generator type	Iso-pulse (ROBOFORM 200)
Dielectric fluid	Oil Flux ELF2
Flushing type	Normal submerged
Power supply voltage (V)	200
Reference voltage (V)	70
Pulse current (A)	8,12,16,20, 24
Polarity	Positive
Pulse on-time (μ s)	12.8, 25, 50, 100
Pulse interval (μ s)	6.4
Tool material	Commercial pure copper
Tool shape	Cylindrical (\varnothing 18.3mm and L=20mm)

Table 4. The average values for the white layer thickness (WT) and depth of heat affected zone (HD) at different machining settings.

Settings	Average WT(μ m)	Average HD(μ m)	Settings	Average WT(μ m)	Average HD(μ m)
8A,12.8 μ s	7.3	12.0	16A,50 μ s	17.75	23.5
8A,25 μ s	8.6	15.7	16A,100 μ s	22.5	32.7
8A,50 μ s	19.3	24	20A,12.8 μ s	7	12
8A,100 μ s	23.4	34.4	20A,25 μ s	10	16.2
12A,12.8 μ s	7.5	12.5	20A,50 μ s	16	21.5
12A,25 μ s	11	16.5	20A,100 μ s	20	30.2
12A,50 μ s	18.8	23	24A,12.8 μ s	6.5	11
12A,100 μ s	22.3	34.8	24A,25 μ s	8.3	15
16A,12.8 μ s	7.7	13	24A,50 μ s	14.2	21
16A,25 μ s	10.7	17.8	24A,100 μ s	20.5	29.6

2 Results and Discussion

2.1 Effect of pulse on-time and pulse current on machining characteristics

The correlation between machining characteristics and pulse on-time in machining of AISI H13 tool steel using copper electrode are shown in Figs. 4~6. According to these figures, an increase in the pulse on-time causes an increase in the MRR and R_a , but a decrease in the TWR. By the increase in pulse on-time, the discharge energy of the plasma channel and the period of transferring of this energy into the electrodes increase. This phenomenon leads to the formation of a bigger molten material crater on the workpiece which results in a higher surface roughness. However, the dimension of plasma channel and the effect of thermal conductivity of electrodes in dispersing the thermal from the spark collision position increase by the increase in pulse on-time. Consequently, by the dispersing more heat from the spark stricken position and increasing the amount of heat transferred from the plasma channel to the electrodes, the plasma channel's efficiency in removing molten material from the molten crater at the end of each pulse decreases, while the dimensions of the molten crater on the electrodes increases. This effect is more pronounced for copper electrode, since its thermal conductivity is much higher than the workpiece's. As a result, the tool wear ratio decreases by increase in pulse on-time.

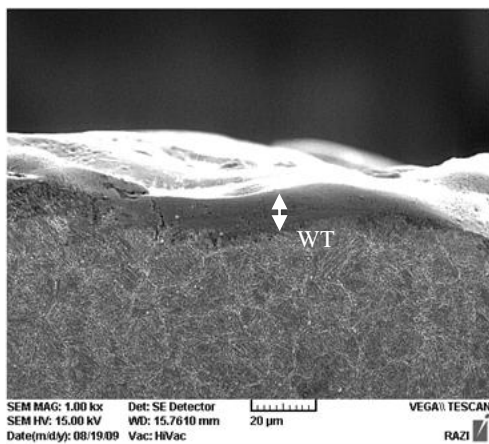


Fig. 1 SEM micrograph showing the white layer of EDMed workpiece ($I=8A$ and $Ti=25\mu s$).

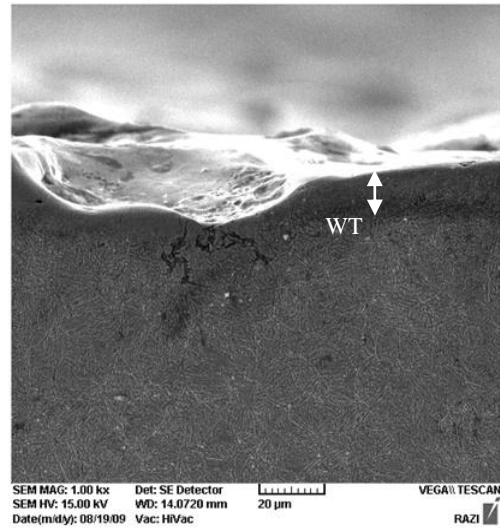


Fig. 2 SEM micrograph showing the white layer of EDMed workpiece ($I=24A$ and $Ti=50\mu s$).

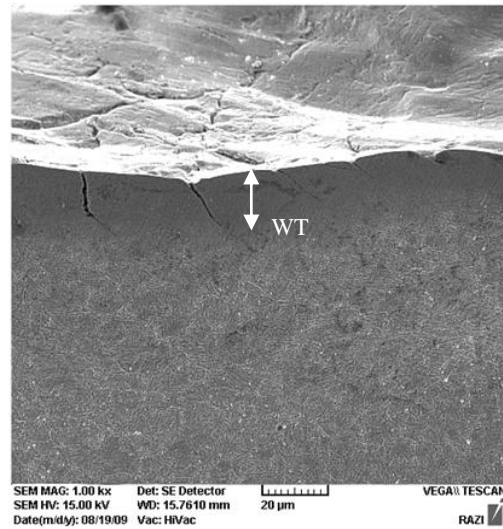


Fig. 3 SEM micrograph showing the white layer of EDMed workpiece ($I=24A$ and $Ti=100\mu s$).

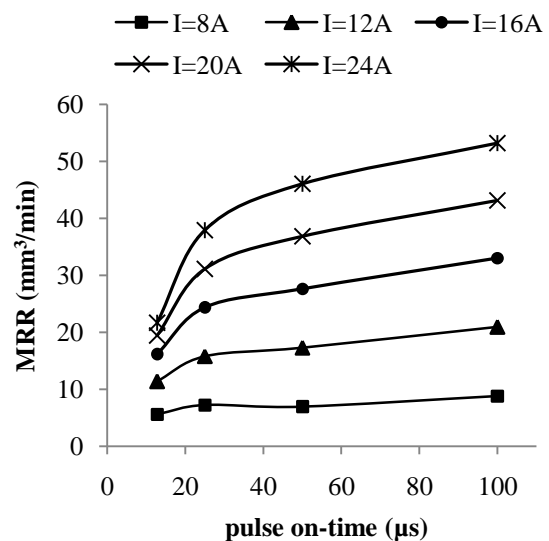


Fig. 4 MRR vs. pulse on-time

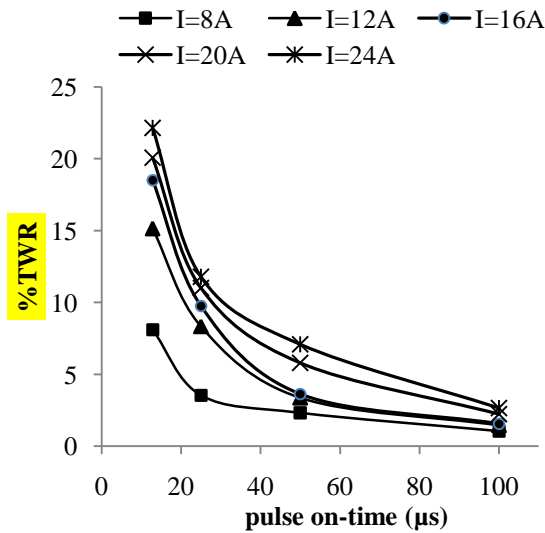


Fig. 5 TWR vs. pulse on-time.

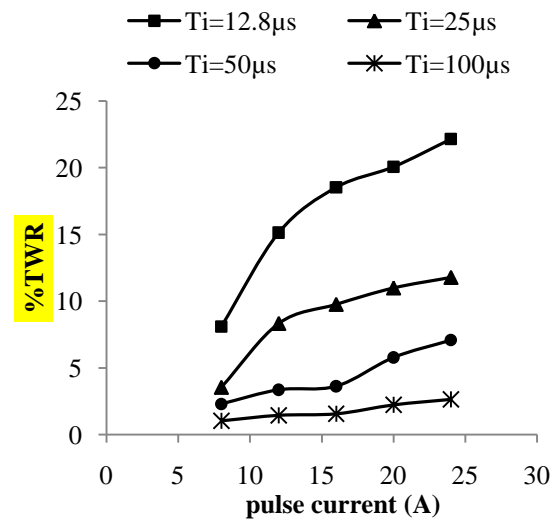


Fig. 8 TWR vs. pulse current.

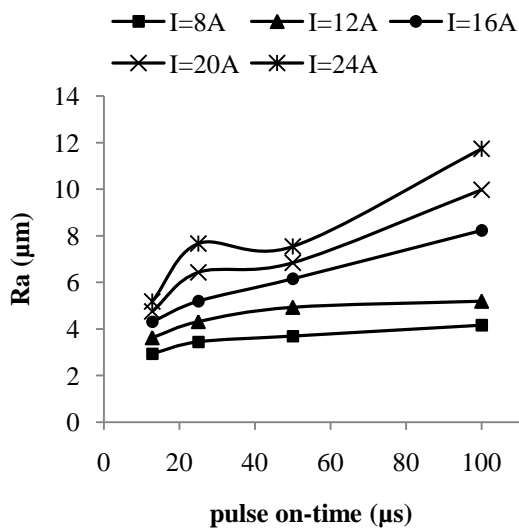


Fig. 6 Ra vs. pulse on-time.

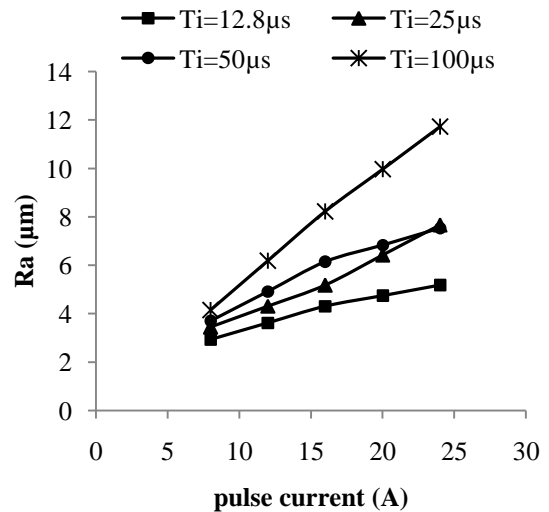


Fig. 9 Ra vs. pulse current.

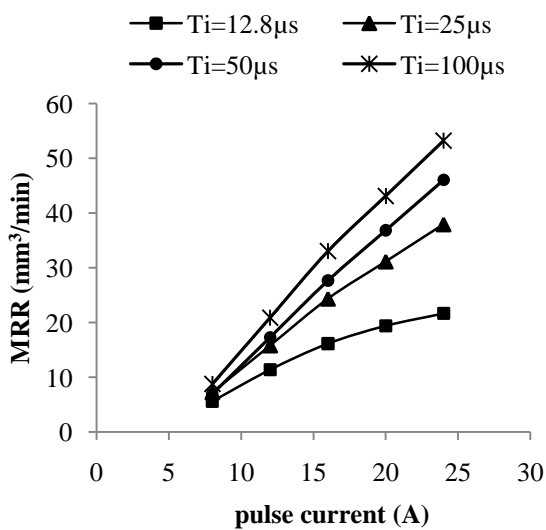


Fig. 7 MRR vs. pulse current.

Figures 7~9 show that MRR, TWR, and R_a increase with augments of the pulse current. Such results were expected as it is obvious that a higher current causes a stronger spark which results in more eroded material for both electrodes.

At a low current, a small quantity of heat is generated and a substantial portion of it is absorbed by the surroundings, as a result, the amount of utilized energy in melting and vaporizing the electrodes is not so intense. But by the increase in pulse current and with a constant amount of pulse on-time, a stronger spark with higher thermal energy is produced, and a substantial quantity of heat will be transferred into the electrodes. Furthermore, as the

pulse current increases, discharge strikes the surface of the sample more intensely, and creates an impact force on the molten material in the crater and causes more molten material to be ejected out of the crater, so the surface roughness of the machined surface increases.

2.2 Effect of Pulse on-time and pulse current on surface integrity

The increase in the thickness of white layer and depth of heat affected zone by the increase in pulse on-time can be obviously seen from the experimental results (Figs. 10 and 11). The justification for this phenomenon is that the plasma flushing efficiency has a strict effect on the white layer thickness. With an increase in pulse on-time, plasma flushing efficiency decreases, as a result, the ability of plasma channel for ejecting the molten material from the molten puddle decreases. Subsequently, this remained molten material in the molten puddle re-solidifies and forms the white layer upon the machined surface. Furthermore, the increase of discharge duration increases the amount of the conducted heat into the workpiece during each discharge, and consequently, more underlying material is affected by the high temperature. Overly, this phenomenon causes the increase in the white layer thickness and heat affected zone.

In other words, better explanation is that the amount of molten material which can be flushed away at the end of each discharge is dependent on the plasma flushing efficiency (%PFE). Clearly the %PFE is dependent on the discharge energy (W), energy gradient (dW/dt), geometrical dimensions of the gap and molten material crater, pressure of the gap (P), and gap pressure gradient (dP/dt). Depending on the amount of mentioned parameters, plasma flushing efficiency decreases as pulse on-time increases. The cause of this phenomenon could be justified by this reason that the increase in pulse on-time causes to decrease in the energy changing rate, as this causes a

major increase in diameter while not much increase in the average temperature of the plasma channel, which leads to decrease in the pressure of the gap and its changing rate. So, regarding to the mechanism of bulk boiling phenomena, the amount of molten material, which is ejected from the molten material crater at the end of discharged, decreases and as a result, the %PFE decreases.

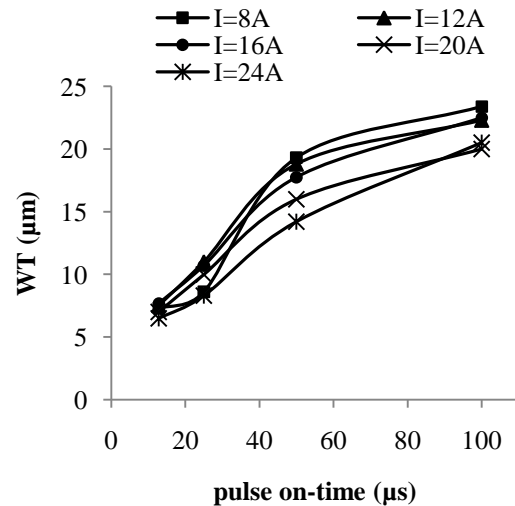


Fig. 10 WT vs. pulse on-time.

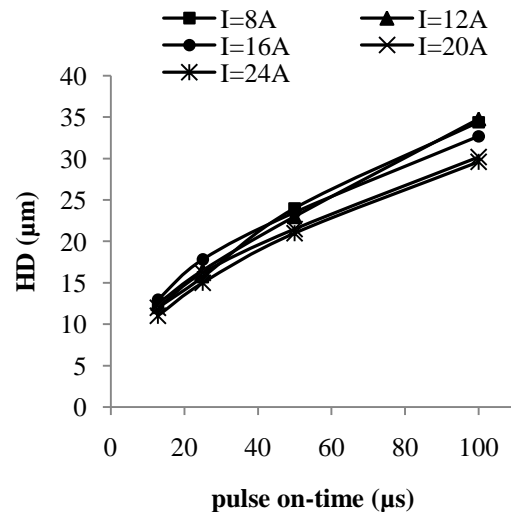


Fig. 11 HD vs. pulse on-time.

From Figs. 12 and 13 it is clear that, increasing the pulse current has a very small effect on the white layer thickness and depth of heat affected zone. Although an increase in pulse current leads to the increase in the dimensions of the molten crater and the heat penetrating depth, the plasma flushing efficiency increases as pulse current increases. The

increase in plasma flushing efficiency causes more molten material to be swept away from the molten crater, therefore thinner layer of re-deposited material appears on the surface of workpiece. Since an increase in the penetrating depth of heat into the workpiece and plasma flushing efficiency counterbalance each other's effect, an increase in the pulse current has no significant effect on the depth of the heat affected zone.

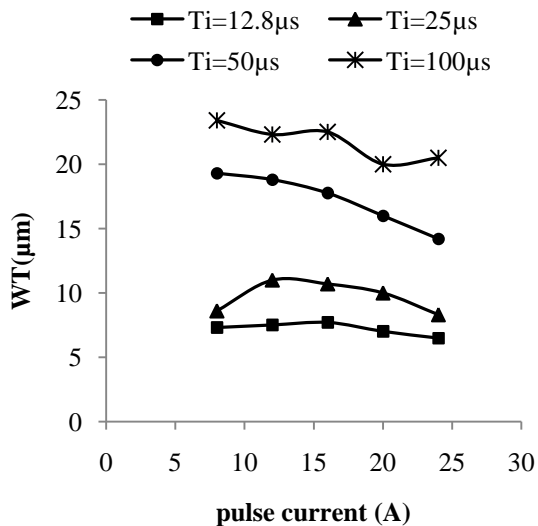


Fig. 12 WT vs. pulse current

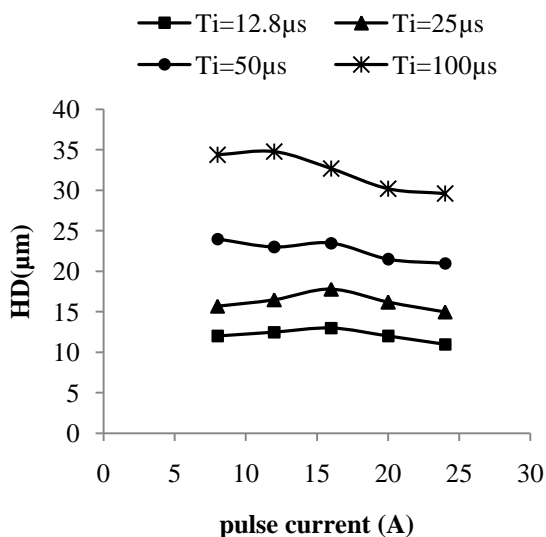


Fig. 13 HD vs. pulse current.

Furthermore, with an increase in the pulse current and with a constant amount of pulse on-time, causing sharp rise in average temperature of the plasma channel [14], the energy gradient increases which leads to increase in the pressure of gap. So,

regarding about the mechanism of bulk boiling phenomenon, the amount of molten material, which is ejected from the molten puddle at the end of each discharge, increases and as a result, the %PFE increases (Ref. [15]) as the reports of Marafona et al. prove this matter [10].

3 Conclusion

Results from an experimental investigation on the effect of machining parameters on EDM process characteristics have been presented. The leading conclusions are as follows:

1. The increase in pulse on-time leads to the increase in the material removal rate, surface roughness, as well the white layer thickness and depth of heat affected zone.
2. The increase in pulse current leads to the sharp increase in the material removal rate and surface roughness.
3. The tool wear ratio decreases by the increase of pulse on-time, and increases by the increase in the pulse current.
4. Slight decrease could be observed in the white layer thickness by an increase in the pulse current.
5. By constant level of discharge energy, high pulse current and low pulse on-time leads to reduction in the white layer thickness and depth of heat affected zone on the surface of EDMed workpiece.

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