

Study on the Effects of Hierarchical Wavy Morphology on Clearance Flow

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This paper aims to explore the influences of multilevel sinusoidal structures on clearance flow by using numerical and experimental methods. A hierarchical sinusoidal morphology was proposed to design the gap between matching surfaces in water hydraulic systems. The specimens with the 0th order, the 1st order and the 2nd order sinusoidal structures were machined by a three dimensional (3D) printer, and their clearance leakage flow was tested on a water hydraulic annular clearance test rig. An extensive simulation study on the effects of waved surfaces with varying amplitudes and wavelengths on leakage was presented. Both the experimental and numerical results show that introducing hierarchical morphology on clearance surfaces will reduce leakage. Moreover, it was found that the leakage decreases with the increase of the ratio of the amplitude to wavelength. Further study of the flow field reveals that the leakage reduction of the 2nd order sinusoidal model is obtained due to the extra vortexes of various scales and the narrower width of the main flow and lower velocity. Moreover, our results indicate that the waved surface induces a micro-hydrodynamic effect that creates an additional load carrying capability, which is helpful for separating the matching surfaces to reduce wear. The study is beneficial to investigate the potential for improving efficiency through the optimization of gap design.

Keywords: hierarchical sinusoidal morphology, clearance flow, water, leakage

Highlights

- A hierarchical sinusoidal morphology was proposed to design matching surfaces clearances.
- The effects of waved surfaces with different amplitudes and wavelengths on leakage were investigated.
- Hierarchical vortexes were found, load carrying ability and fluid erosion were discussed by analysing the pressure and velocity fields in the hierarchical sinusoidal models.
- Hierarchical morphology on matching surfaces not only can reduce leakage but also has advantages for reducing mechanical wear and fluid erosion, which is difficult by narrowing gaps.

0 INTRODUCTION

Clearances broadly exist in hydraulic components, such as the matching clearances of piston/cylinder, swash plate/slipper pad and cylinder block/valve plate, etc., in which most of the energy is dissipated by friction and leakage [1]. With the increasing demand for an environmentally friendly, non-flammable, readily available and hygienic fluid medium in hydraulic systems, water used as a pressure medium has caused renewed interest. However, the kinematic viscosities of water and mineral oil are 1 m²/s and 29 m²/s at room temperature at atmospheric pressure, respectively. Lower viscosity is accompanied by poorer lubricity and larger leakage. For certain matching clearances, the leakage rate of water is larger than that of oil, which will cause more internal and external leakages for water hydraulic systems [2]. Therefore, smaller clearances have to be considered in order to achieve reduced leakage. However, narrower gaps in water hydraulic components will cause mechanical wear [1] and [3] and fluid erosion [4] due

to the poor lubrication of water, which will enlarge gaps, leading to more leakage [5].

Surface topography technology has emerged in recent years as an effective method to reduce energy dissipation [6] to [8]. Recent works on various forms and shapes of surface texturing for high efficiency [9] and [10], energy-saving [11] and [12] and long performance life [13] and [14] have been carried out, which has already succeeded in many industrial applications [8], [15] and [16], such as seals [17] and [18], bearings [19] and [20] and gears [21] and [22]. An attempt to optimize piston topography to minimize energy dissipation within the piston cylinder interface was made by Wondergem and Ivantysynova [23] and Ivantysynova [24], who proposed a barrel-like piston. Ivantysynova and Lasaar [25] demonstrated the potential of an advanced gap design using computer simulation. The load carrying ability, piston friction force and gap flow were computed for all investigated surface variations, and then an improved barrel-like piston was proposed to reduce energy dissipation generated by piston/cylinder assembly. Kleist [26] also studied pistons with different shapes for radial piston

machines. The results showed that the piston with surface morphology has lower friction and leakage comparable to the traditional one. Ivantysynova and Baker [27] applied a sinusoidal micro-structured waved surface to the valve plate gap surface for reducing power loss, and their results show that the waved surface significantly reduce power losses at lower operating pressures; however, the leakage of waved surface designs are higher than that of the standard designs, which is caused by larger gap heights. Pelosi and Ivantysynova [28] numerically studied the cylinder block with a brass bushing. Their results showed that the wavy surface, caused by the thermal deformation of the brass bushing, has an impact on the energy dissipation generated by viscous friction and leakage flow. Shin and Kim [29] studied the influence of various peak-to-valley amplitudes and wavelengths of surface waviness on leakage power loss and friction power loss. Their results revealed that proper surface design can improve reliability and power efficiency. Shen and Khonsari [10] investigated the tribological and sealing performance of a piston ring with a specially designed textured surface in a diesel engine. They found that lasered pockets led to a reduction of up to about 15 % in the total friction between cylinder liner and piston assembly and also improved the sealing performance compared to untextured piston rings. For piston ring-liners (PRL), recent developments in ring surface modification through laser surface texturing have shown promising results in improving tribological characteristics. Usman and Park [12] considered asymmetric PRL contact of a textured piston ring in a distorted bore, and found that optimized surface textures improve the tribological performance of a PRL interface, whereas textures with large lateral aspect ratios have a detrimental effect. Rao et al. [16] studied the performance of the cylinder liner-piston ring with different surface textures (1 mm, 2 mm, 3 mm, and 4 mm widths) in marine diesel settings; the results showed that the 2 mm groove structure of the cylinder liner is more favourable for improving the wear performances at low speed, whereas a 3 mm groove structure of the cylinder liner is more suitable for improving the wear performance at higher speeds. Taken together, plentiful efforts have been carried out to improve the tribological properties and sealing performance via the rational design of surface morphology. However, little attention is paid to the effects of hierarchical morphology on the gap flow. Interestingly, many biological materials are hierarchically structured with wavy morphology, for example, towel gourd tendrils [30] and bovine horns [31].

Inspired by the unique hierarchical structures in nature, this paper proposed a hierarchical sinusoidal morphology for designing clearances between matching surfaces in water hydraulic systems in which poorer lubricity and larger leakage occur due to the lower viscosity of water. We tested the leakage flow of the models with 0th order, 1st order, and 2nd order sinusoidal structures on the water hydraulic annular clearance test rig. Further studies on the effects of waved surfaces with various amplitudes and wavelengths on leakage were carried out using numerical simulation. The velocity and pressure fields generated in the clearances were analysed to give further explanations of experimental observation. Both the experimental and simulated results suggest that hierarchical sinusoidal structures in the clearances between matching surfaces are beneficial to leakage reduction.

1 EXPERIMENTAL

1.1 Generation of the 2nd Order Sinusoidal Hierarchical Wave

The 2nd order sinusoidal curves were obtained based on the following equations[31]. As shown in Fig. 1, the sine arc length from the origin point O to an arbitrary point $N(p_1, q_1)$ can be described as follows:

$$s = \int_0^p \sqrt{1 + (dq_1/dp_1)^2} dp_1 \\ = \int_0^p \sqrt{1 + \left[\frac{2\pi A_1}{\lambda_1} \cos\left(\frac{2\pi}{\lambda_1} p_1\right) \right]^2} dp_1, \quad (1)$$

where A_1 and λ_1 are the amplitude and wavelength of the 1st order sinusoidal curve C_1 , p_1 and q_1 are horizontal and vertical coordinates, respectively. The sinusoidal 2nd order hierarchical wave C_2 is superimposed on the 1st order wave, and its amplitude A_2 and wavelength λ_2 can be calculated on the curvilinear coordinate system along C_1 :

$$q_2 = A_2 \sin\left(\frac{2\pi}{\lambda_2} s\right). \quad (2)$$

Likewise, the 2nd order sinusoidal curve can be described by the equation in the XOY coordinate system with p as its free parameter:

$$x = p_1 - q_2 \sin \alpha, \quad (3)$$

$$y = q_1 + q_2 \cos \alpha, \quad (4)$$

where α is given by

$$\alpha = \tan^{-1} \left[\frac{2\pi A_1}{\lambda_1} \cos \left(\frac{2\pi}{\lambda_1} p_1 \right) \right]. \quad (5)$$

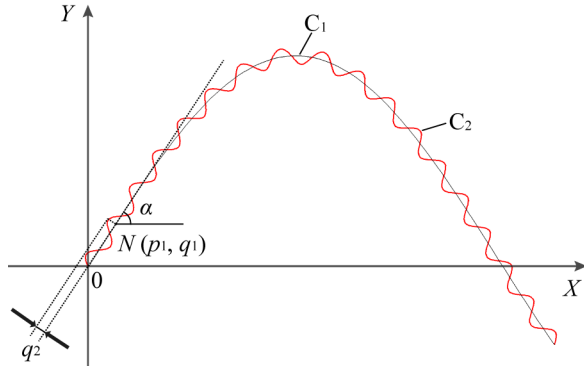


Fig. 1. Illustration of the method for generating the 2nd order hierarchical wave

1.2 Test Specimens

Three kinds of models were designed: 0th order model, 1st order sinusoidal model, and 2nd order sinusoidal model, as shown in Fig. 2. The clearance, δ , equals 0.2 mm. Compared to the 0th order model, the 1st order model is characterized by sinusoidal waviness with amplitude A_1 and wavelength λ_1 . The 2nd order model has two-level hierarchical sinusoidal structures; apparently, it was superimposed on the 1st order sinusoidal structure with the amplitude $A_2 < A_1$ and wavelength $\lambda_2 < \lambda_1$.

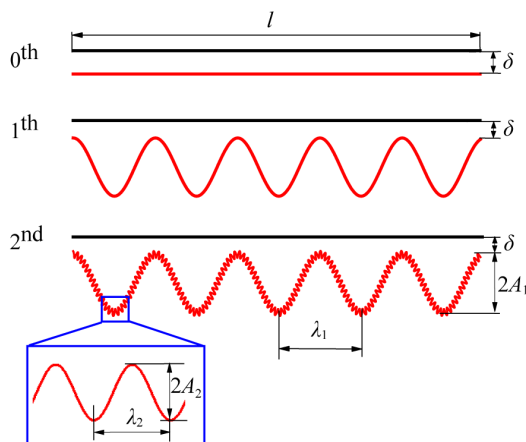


Fig. 2. The clearance models with the 0th order, the 1st order, and the 2nd order sinusoidal morphology

Three dimensional (3D) printing technology was considered to manufacture these models, and

Lite 600 3D printer with 0.05 mm print precision was employed. The material used is Acrylonitrile Butadiene Styrene (ABS). The parameters of the 3D printed specimens are shown in Table 1, while 3D printed specimens are shown in Fig. 3. The whole length of the specimen is 131 mm, including both the work length 111 mm and the interference fit length 10 mm on its either ends. Enlarged views of the specimen are shown in Fig. 4.

Table 1. The design and printed parameters of specimens

Specimen	0 th order	1 st order	2 nd order
Designed amplitude and wavelength [mm]	$\lambda_1=0$ $\lambda_2=0$ $A_1=0$ $A_2=0$	$\lambda_1=10$ $\lambda_2=0$ $A_1=0.1250$ $A_2=0$	$\lambda_1=10$ $\lambda_2=1$ $A_1=0.1250$ $A_2=0.0500$
Printed amplitude and wavelength [mm]	$\lambda_1=0$ $\lambda_2=0$ $A_1=0$ $A_2=0$	$\lambda_1=10.0030$ $\lambda_2=0$ $A_1=0.1242$ $A_2=0$	$\lambda_1=10.0012$ $\lambda_2=1.0063$ $A_1=0.1310$ $A_2=0.0637$
Design diameter [mm]	31.6000	31.6000	31.6000
Printed diameter [mm]	31.5460	31.5333	31.0547
Design clearance [mm]	0.2000	0.2000	0.2000
Printed clearance [mm]	0.2271	0.2334	0.4727

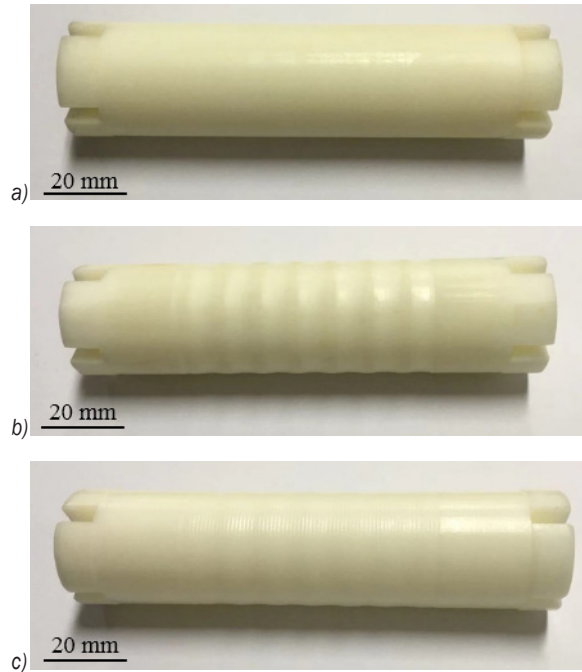


Fig. 3. The specimens: a) the 0th order model, b) the 1st order model and c) the 2nd order model

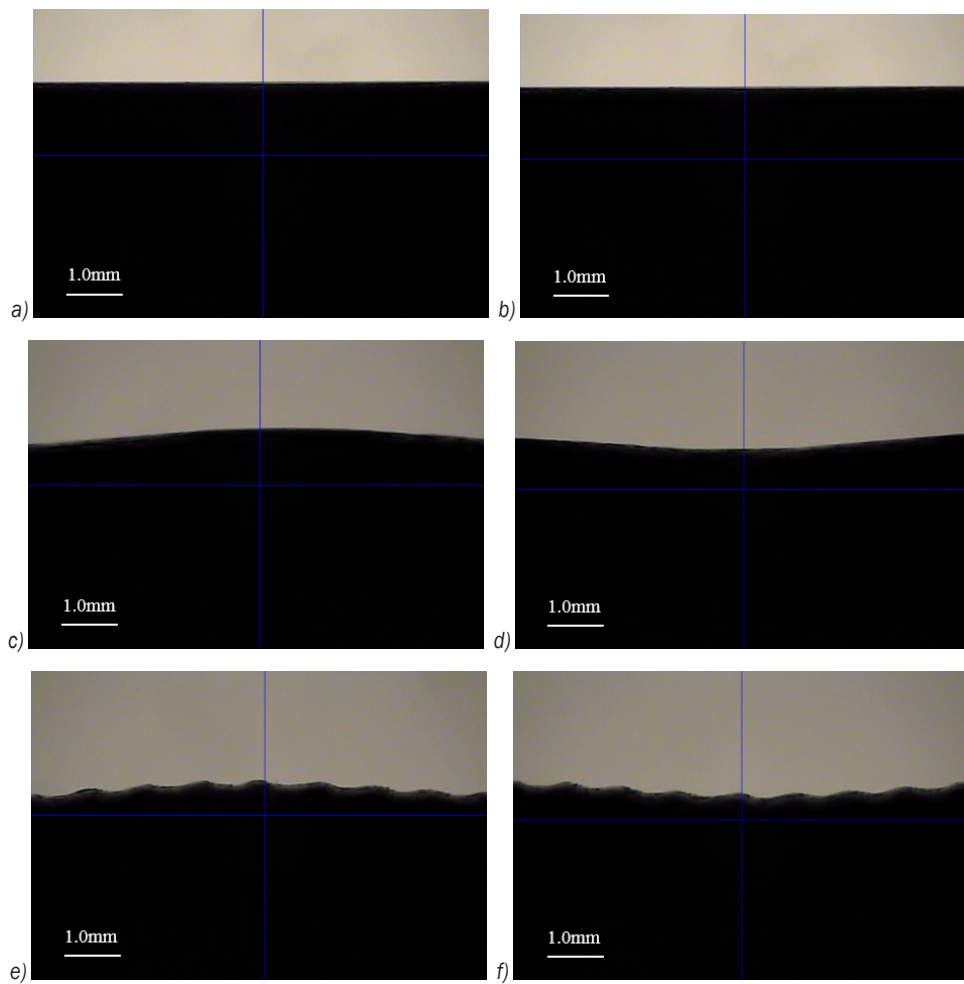


Fig. 4. The enlarged views: a) and b) the 0th order specimen, c) and d) the 1st order specimen, e) and f) the 2nd order specimen

1.3 Test Procedure and Results

In our leakage experiments, the internal diameter of the cylinder was 32.0 mm. As shown in Fig. 5, the interference fits between the cylinder and both ends of specimens were used to ensure the same clearance in the circumferential. The water pump was used, and the pressure difference between the inlet and outlet of the test cylinder was set to 0.2 MPa by regulating the throttle valve. The flow through the clearance between the cylinder and specimen was measured by the flow sensor. Clearance leakage flow of the 0th, the 1st, and 2nd order specimens were tested respectively on the water hydraulic annular clearance test rig. Obtained experimental data are displayed in Table 2. The results showed that the specimen with 2nd order structures has the largest gap size but the lowest leakage. It is well known that the larger clearance size will result

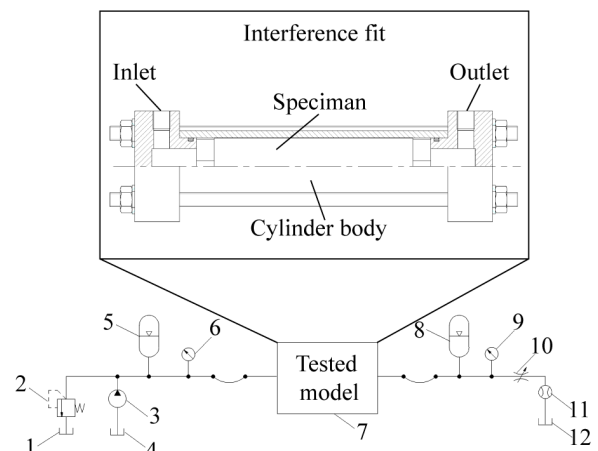


Fig. 5. The schematic of the water hydraulic annular clearance test rig (1, 4, 12 water tank, 2 hydraulic relief valve, 3 water pump, 5, 8 accumulator, 6, 9 pressure sensor, 7 tested model, 10 throttle valve, 11 flow sensor)

in larger leakage flow. Therefore, compared to the 0th order and the 1st order structures, the 2nd order structures can more effectively reduce the clearance leakage. Furthermore, the mechanism underlying the reduced leakage caused by the 2nd order structures was still unclear; thus, the numerical simulation was used to further study the effect of hierarchical sinusoidal morphology on clearance flow.

Table 2. A comparison of numerical simulation results with experimental data

Specimen	0 th order	1 st order	2 nd order
Leakage by experiment [kg/s]	0.1352	0.1647	0.1302
Leakage by simulation [kg/s]	0.1426	0.1794	0.1421
Deviation [%]	5.5	8.9	9.1

2 NUMERICAL APPROACH

Reynolds number is the criteria to estimate the flow state, and it is defined as follows:

$$\text{Re} = \frac{\rho v d_H}{\mu}, \quad (6)$$

where ρ is the density, v is the velocity, μ is the viscosity, and d_H is the hydraulic diameter. For the annular gap, $d_H = 2h$, h is the unilateral clearance size. Critical flow q_c can be written as:

$$\begin{aligned} q_c &= A v_c = \frac{\text{Re}_c \mu}{\rho d_H} \cdot \pi (r_1 + r_2) h \\ &= \frac{\text{Re}_c \mu \pi (r_1 + r_2)}{2\rho}, \end{aligned} \quad (7)$$

where Re_c is the critical Reynolds number, r_1 is the inner radius of the cylinder, and r_2 is the radius of the specimen. While the flow is larger than q_c , the fluid flow transfer is from laminar to turbulent. For the tested models, the mass flow is larger than q_c ; then it can be deduced that turbulent flow is generated in the clearance between the specimen and the cylinder.

Leakage flow is defined by the pressure difference over the seal. The clearance sealing performance of water hydraulic components under various pressure difference have been studied: 0.02 MPa [32], 0.2 MPa [33] and [34], 0.4 MPa [33], 0.41 MPa [35], 0.6 MPa [33], 1.5 MPa [36], 2 MPa [36] and [37], 2.5 MPa [36], 5 MPa [38], 10 MPa [38], 15 MPa [38], 20 MPa [38]. In this article, the pressure difference between the inlet and outlet was set as 0.2 MPa. A two-dimensional (2D) axisymmetric model was adopted, and water

was chosen as the working fluid. The clearances of the 0th order, the 1st order, and the 2nd order models were set as 0.2271 mm, 0.2334 mm, and 0.4727 mm, respectively, which were consistent with the clearance sizes used in experiments. To replicate conditions of the experimental setup, matching surfaces were treated as wall boundaries for numerical simulations. This study has been carried out with the commercial computational fluid dynamics (CFD) package from ANSYS FLUENT. A re-normalisation group (RNG) $k-\varepsilon$ model was used to predict the clearance turbulent flow. This model is a two-equation turbulence model that is derived by using renormalization group methods [39]; it significantly improves the responsiveness to the effects of rapid strain and streamline curvature [40] and [41] and predicts more swirls and has better treatment of near-wall turbulence effects [42] and [43]. It predicted well the numerical results that agree with experimental results. The SIMPLEC algorithm is implemented in FLUENT, and the pressure-based solver and Green-Gauss node-based gradient treatment were chosen to obtain fast and accurate converging solutions for unstructured triangular grids. 2nd order discretization scheme was used for all governing equations. The desired convergence target was that the root mean square residuals of the momentum and mass equations, energy equation, and turbulence equations would reach 10^{-5} .

The whole mesh generation process was carried out in Pointwise 17.4 software. The computational model was qualified with unstructured triangular mesh, and the schematic diagrams of the grid are shown in Fig. 6. Refined meshes are adapted at both the inlet/outlet and wall boundaries to capture the detailed flowing behaviour, while relatively coarser mesh was used in other regions. Furthermore, grid dependence and convergence studies were performed, as depicted in Fig. 7. The selected nodes number of computational models in this paper is around 150,000 to 200,000. With this resolution, obtaining a stationary solution required approximately 200 minutes on an Intel E5 workstation with 32G/2133ECC. Finally, the mass flow of the 0th order, the 1st order and the 2nd order models were calculated numerically. The results are shown in Table 2; it can be seen from the numerical simulation results that the 2nd order one has the least leakage flow, and the 1st order one is with the largest flow. Furthermore, numerical simulation has shown a good agreement with experimental data, with errors of less than 10 %. The simulation methods were verified with our experiments.

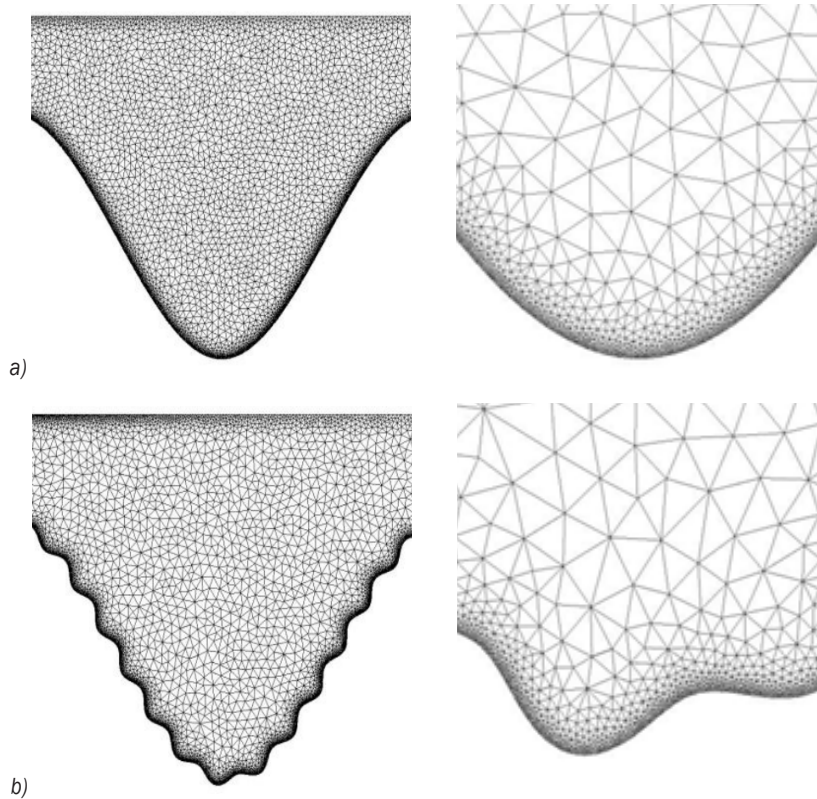


Fig. 6. Meshes used for models: a) The 1st order model; b) the 2nd order model

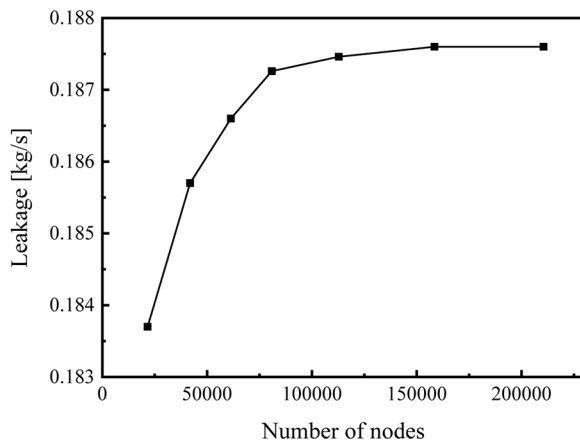


Fig. 7. An example of grid dependence of the CFD results

3 THE EFFECT OF VARIOUS SINUSOIDAL MORPHOLOGY ON LEAKAGE

3.1 Simulation Models

The numerical investigation for the effect of multilevel sinusoidal morphology on leakage was carried out

with various amplitudes and wavelengths. Matching surfaces were assumed to be rigid bodies, and the temperature of the fluid was assumed to be constant in this paper, in order to focus on the influences of the surface morphology on clearance flow. The 1st order models were controlled by the amplitude A_1 of 0.25 mm, 0.5 mm and 1.0 mm, and the wavelength λ_1 within the range of 0.125 mm to 10 mm. The parameters of the 2nd order model, A_2 equals to 0.01 mm, 0.03 mm and 0.05 mm, respectively, and λ_2 takes value in 0.02 mm to 0.4 mm. As shown in Fig. 2, three kinds of 2D axisymmetric models were calculated. The length, l , was set to be 10 mm, the clearance, δ , equals to 0.2 mm.

3.2 Influence of the 1st Order Sinusoidal Morphology on Sealing Performance

A dimensionless parameter, Q_1/Q_0 , was introduced to estimate the seal efficiency of the 1st order model compared to the 0th order one, and another dimensionless parameter, ε_1 , was defined by A_1/λ_1 , to characterize the surface shape of the 1st order sinusoidal morphology. Firstly, the 0th order

model was simulated numerically, giving numerical leakage flow of $Q_0=0.5545$ kg/s. Similarly, leakage Q_1 for the waved surface of varying amplitudes and wavelengths, for 1st order models were obtained and compared with the 0th order model under the same operating conditions. As shown in Fig. 8, the water leakage Q_1/Q_0 decreases firstly and then increases with the increments in parameter ε_1 . The lowest leakage Q_1 was achieved at $A_1=1$ mm, $\varepsilon_1=4$ with up to 43.3 % reduction in $(1-Q_1/Q_0)$. However, as the small value of parameter ε_1 is taken, the sealing performance is worsened by the 1st order sinusoidal structure. Specifically, as the value of ε_1 is less than 0.15, 0.2 and 0.4 for the three models respectively ($A_1=0.25$ mm, 0.5 mm and 1.0 mm), the value of Q_1/Q_0 is more than 1.

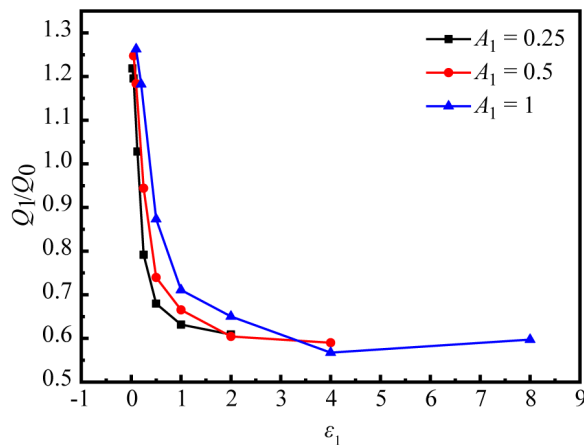


Fig. 8. The seal efficiency of the 1st order models

3.3 Influence of the 2nd Order Sinusoidal Morphology on Sealing Performance

The 2nd order models with sinusoidal morphology superimposed on the 1st order model of $A_1=0.25$ mm and $\lambda_1=1$ mm were established and computed. The dimensionless parameter ε_2 was defined by A_2/λ_2 , to characterize the waved shape of the 2nd order sinusoidal morphology. Fig. 9 depicts the sealing efficiency of the 2nd order sinusoidal morphology models. The leakages of the 2nd order models are lower than that of the 1st order models. In detail, it can be seen that the maximum leakage reduction $(1-Q_2/Q_1)$ is 18 %, which means the sealing efficiency is effectively improved by the 2nd order sinusoidal morphology. However, when the parameter ε_2 is relatively small, larger leakage is generated due to the existence of larger clearance fields and less energy dissipation.

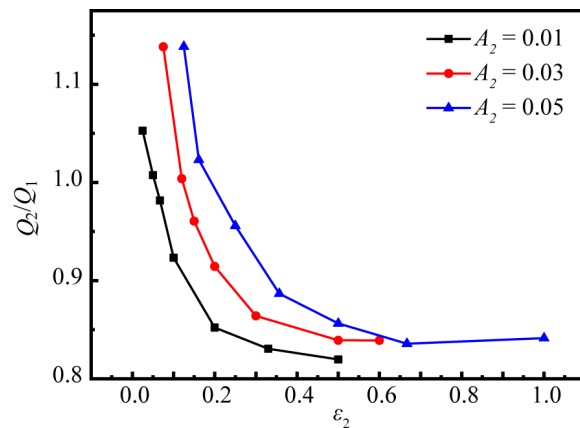


Fig. 9. The seal efficiency of the 2nd order models

4 FLUID FIELD ANALYSIS

To further explore the sealing performance of the 1st order and the 2nd order models, their streamlines distributions were plotted in Figs. 10a and b, respectively. The enlarged local views of the 2nd order wavy teeth were also presented in Fig. 10c for better observation. As indicated in Fig. 10a, one big rotating vortex is observed in each cell of the 1st order model, which causes a decrease in leakage by dissipating fluid kinetic energy. Similarly, for the 2nd order model, a big vortex is also generated in the middle region of each cavity, as shown in Fig. 10b. More interestingly, numerous 3rd order vortices with reverse rotation can be found in the 2nd order wavy cavities. Moreover, the tertiary vortices can also be found at the teeth tips of the throttling area of the 2nd order model, as shown in Fig. 10c. All the vortices in various levels will contribute to dissipate more fluid kinetic energy resulting in a reduction in leakage in the case of the 2nd order model. In addition, compared to the 1st order model, a narrower-width main flow was generated by introducing the hierarchical sinusoidal morphology in the 2nd order model, which would lead to less leakage in the 2nd order model.

The velocity of the main flow along the X direction plays a major role in surface wear and gap leakage. The X component of velocity contour was shown in Fig. 11. The results show that the velocity of flow in clearance is 6 m/s to 13 m/s in the 1st order model, but 4 m/s to 11 m/s in the 2nd order model. Lower velocity along the X direction in the 2nd order model helps achieve less fluid erosion between the matching surfaces, and it also gives a further explanation for its lower leakage. The high-velocity fluid through the clearances will cause the fluid

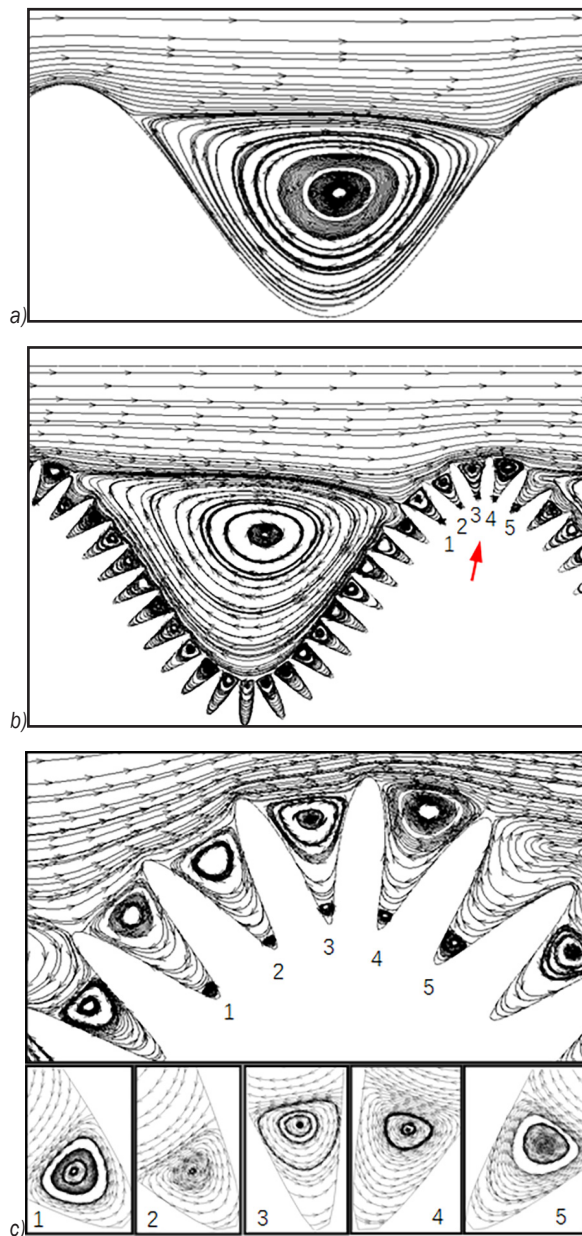


Fig. 10. Streamlines distributions: a) the 1st order model; b) the 2nd order model; c) the enlarged views of the 2nd order models (arrows in b)

erosion, called “wire drawing”. Moreover, the wear of the matching surfaces will also inevitably enlarge the clearance, which will increase the leakage. Fig. 12 depicts the statistical results of velocity magnitudes in the flow field of the 1st order and 2nd order models. The velocity magnitude in about 70 % fluid fields is less than 3 m/s for the 1st order model. Comparatively, about 85 % zones of the 2nd order model are with the velocity of less than 1 m/s.

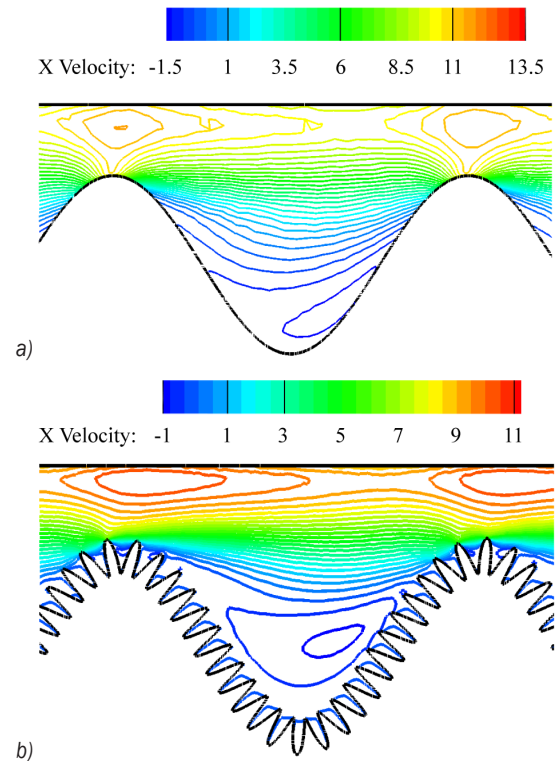


Fig. 11. The X velocity component contours: a) the 1st order model; b) the 2nd order model

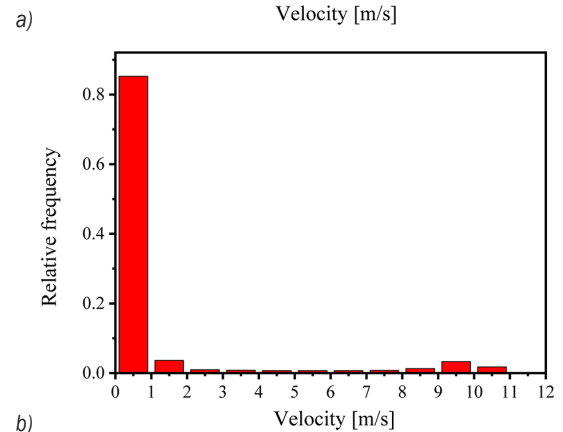
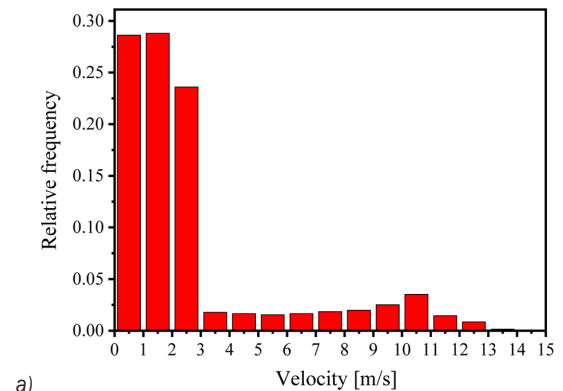


Fig. 12. The statistics of velocity magnitudes in flow fields: a) the 1st order model; b) the 2nd order model

Surfacing texturing is a powerful method of enhancing hydrodynamic load carrying capacity. As indicated in Fig. 13, the pressure distribution of models with the 0th order, 1st order and 2nd order structures were given respectively. Firstly, the pressure decreases smoothly from the inlet to the outlet for the 0th order model but drops gradually for the 1st order and 2nd order models, and the pressure in the 2nd order gap drops faster than that of the other two models. Moreover, the waved surface generated numbers of

convergent wedge-shaped areas in the clearance, causing changes in the thickness of the fluid film, which contribute to additional hydrodynamic pressure generation. As shown in Figs. 13b and c, the pressure mainly dropped at peaks but remained stable in the chambers of waved troughs. Furthermore, for each peak in the waved surface, there is a corresponding peak in the pressure field. A micro-hydrodynamic effect was induced by the waved surface and created an additional load carrying capability, separating the matching surfaces.

5 CONCLUSIONS

The hierarchical sinusoidal morphology was introduced to the clearance of matching surfaces in water hydraulic systems where poorer lubricity and larger leakage exist due to the lower viscosity of water. Both the numerical and experimental results show that introducing hierarchical morphology on matching surfaces will reduce leakage. The models of the 0th order, the 1st order and the 2nd order with various amplitudes and wavelengths were studied. For the 1st order and the 2nd order models, the leakage reduces with the increase in the ratio of the amplitude to wavelength. Further study of the flow field reveals that the significant leakage reductions of the 2nd order sinusoidal models are obtained due to the extra vortexes of various scales in the 2nd order wavy cavities, which dissipate more fluid kinetic energy, contributing towards a mechanism to reduce leakage. In addition, the narrower width of the main flow and lower X component of velocity in the 2nd order models compared to that of the 1st order models also make contributions to the lower leakage. Moreover, the waved surfaces produce changes in the thickness of the fluid film, which contributes to create an additional load carrying capability and reduce wear. We conclude that the exciting results obtained from introducing the hierarchical waved surface have a huge potential application to reduce energy loss in hydraulic systems and give a new way to design clearances between matching surfaces.

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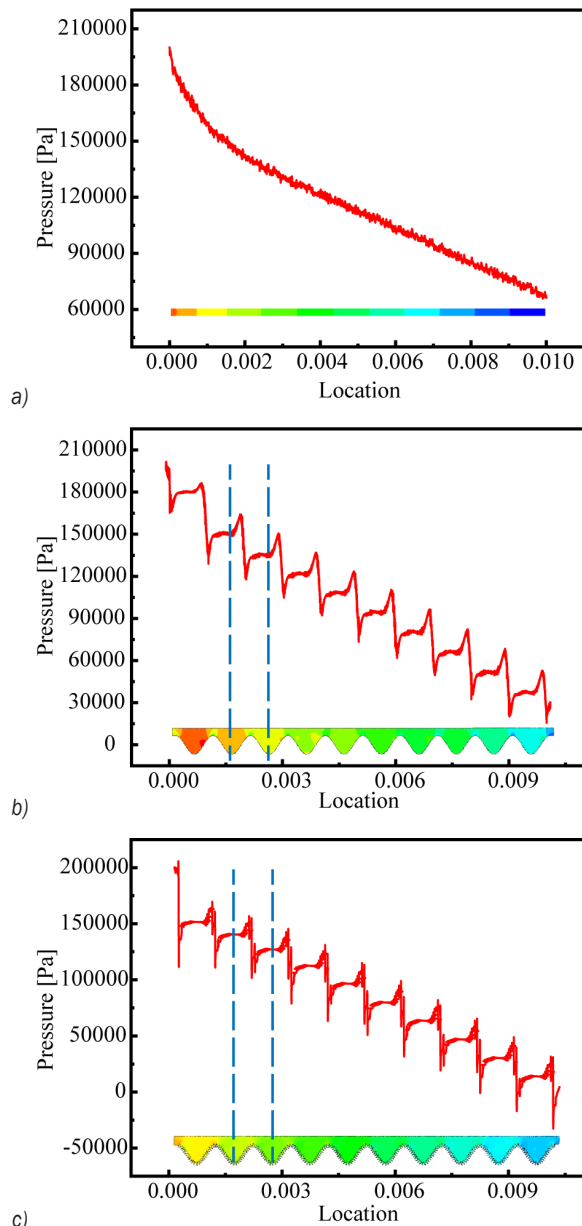


Fig. 13. Comparisons of pressure distribution: a) the 0th order model; b) the 1st order model; c) the 2nd order model

7 NOMENCLATURE

A_1	amplitude of 1 st order cosinoidal waviness, [mm]
A_2	amplitude of 2 nd order cosinoidal waviness, [mm]
λ_1	wavelength of 1 st order consinoidal waviness, [mm]
λ_2	wavelength of 2 nd order consinoidal waviness, [mm]
ε_1	dimensionless parameter, defined by A_1/λ_1
ε_2	dimensionless parameter, defined by A_2/λ_2
Q_0	leakage of straight labyrinth seal, [kg/s]
Q_1	leakage of 1 st order labyrinth seal, [kg/s]
Q_2	leakage of 2 nd order labyrinth seal, [kg/s]
L	length of labyrinth seals, [mm]
δ	clearance of labyrinth seals, [mm]
ρ	density, [kg/m ³]
μ	Viscosity, [Pa·s]
d_H	hydraulic diameter, [mm]
v	Velocity, [m/s]
h	unilateral clearance size, [mm]
q_c	critical flow, [kg/s]

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